

Team Goals

Design, Fabricate, and Analyze a Structure that will Support the Payload

- Space Allocation of All Teams' Components
- Data/Power Cable Routing

EDUCATE STUDENTS

- Programs, and Techniques used in Industry
- Hands-on Experience

Initial Criteria

Volume and Mass Constraints

- Hitch-Hiker Specifications

As close to mass limit as possible to maximize orbital life-time

Constraints Imposed by Other Sub-Systems

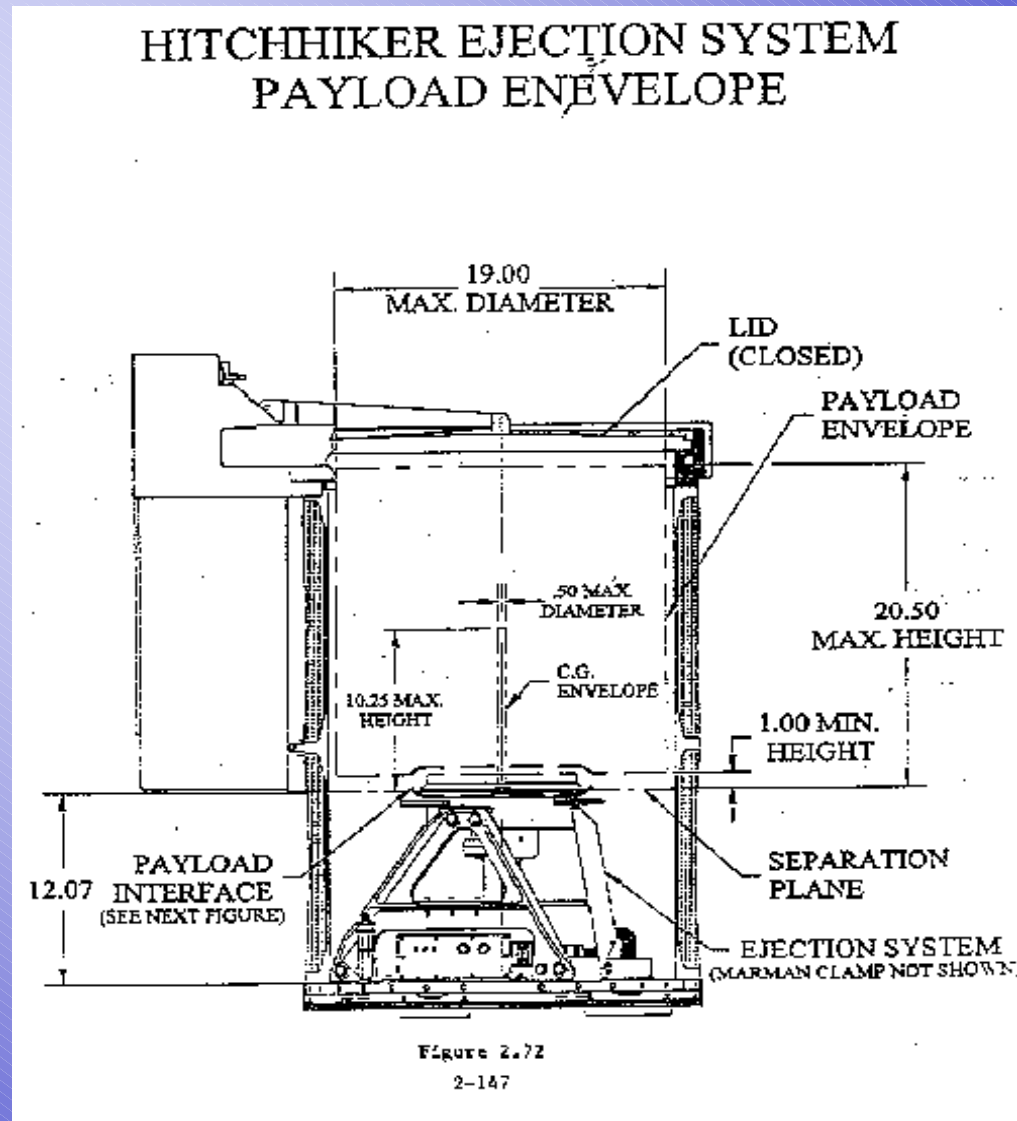
- Science (C.T.E.)
- G.N.C. (Bending/Stiffness)
- Other Teams (Temperature)

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Hitch-Hiker Specifications

Maximum spacecraft weight	68 kg	↔	150 lb
Maximum spacecraft height	52 cm	↔	20.5 in
Maximum spacecraft diameter	48 cm	↔	19 in
Canister inside diameter	50 cm	↔	20 in
Maximum CG location	1.27 cm	↔	0.5 in
Maximum CG location	26 cm	↔	10.25 in
Ejection Velocity	0.6 - 1.2 mps	↔	2 - 4 fps
To Be Determined			
Maximum rotational impulse			
Minimum payload resonant frequency			

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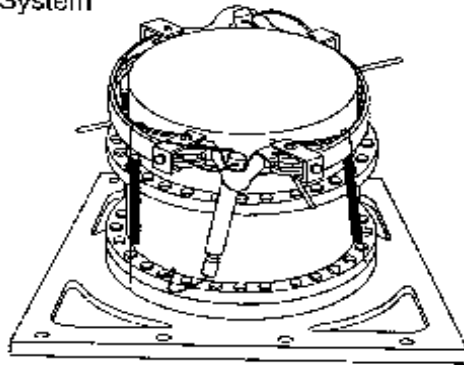


from N.A.S.A. Shuttle Small Payloads Project

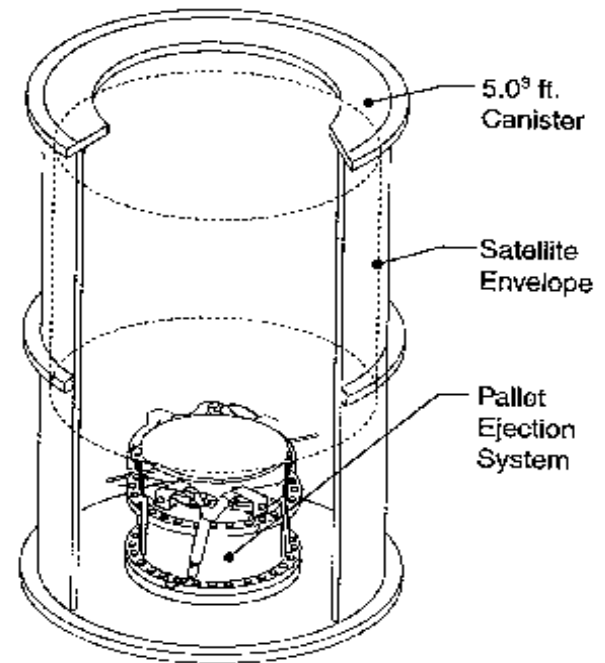
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PALLET EJECTION SYSTEM (PES)

Pallet
Ejection
System



Pallet Configuration



Can Configuration

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**PRO/E DRAWING OF
MARMON PLATE**

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Component/ Subsystem	Operating Temperature C	Survival Temperature C
Digital Electronics	0 , 50	-20 , 70
Analog Electronics	0 , 40	-20 , 70
Batteries	10 , 20	0 , 35
Infrared detectors	-269 , -173	-269 , 35
Momentum wheels, motors	0 , 50	-20 , 70
Solar Panels	-100 , 125	-100 , 125

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Double Cylindrical Design

Inner Telescope Tube (I.T.T.)

- ñ Main Load Bearing Structure
 - Marmon Plate Attachment
- ñ Optical Structure
 - Light Baffles

Outer Solar Structure (O.S.S.)

- ñ Large Surface Area for Solar-Foil
- ñ Supports Solar Electronics

Launch-Interface End

- ñ Support Outer Structure
- ñ May be more complex design than the Aperture End

Aperture End

- ñ Supports Outer Structure

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Simple Design

Minimize number of parts

Use proven methods

Good reason for added complexity

Materials used must survive ground, launch, on-orbit environment, and help control the temperature

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Control Loads and Vibrations Passively

Strategically use highly damped materials

Make natural frequency much different from driving frequency

Mount sensitive components in regions of the structure with low response

Mount actuators in areas that cause little structural excitation

Vibration must not interfere with launch vehicles control system, or it's own control system in deployed configuration

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Dynamics and Loads

Predict natural frequencies, modes, damping

Predict responses to forces and vibrations as function of time

Stress

Predict member loads and stresses to withstand

Strength: single load

Life: cyclic and sustained loading

Stiffness

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Documentation

Requirements

How requirements and designs evolved

Verification Criteria

Deployment Plan

Product Configuration

Manufacturing Process

How Requirements Verified

Critical Data and Math Models

Key decisions, problem resolutions, and rationale

Lessons Learned